L Number	Hits	Search Text	DB	Time stamp
1	63	(electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.	USPAT; US-PGPUB	2003/05/08 12:43
2	21	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque and (speed velocity rate) and position	USPAT; US-PGPUB	2003/05/08 12:22
3	1	(((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque and (speed velocity rate) and position) and numerical	USPAT; US-PGPUB	2003/05/08 12:23
4	4	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and numerical	USPAT; US-PGPUB	2003/05/08 12:41
5	112	388/801	USPAT; US-PGPUB	2003/05/08 12:41
6	148	(electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab. and 388/801	USPAT; US-PGPUB	2003/05/08 12:42
7	0	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and 388/801	USPAT; US-PGPUB	2003/05/08 12:44
8	187	(electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.	USPAT; US-PGPUB	2003/05/08 12:44
9	0	((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.) and 388/801	USPAT; US-PGPUB	2003/05/08 12:44
10	749	318/799	USPAT	2003/05/08 12:53
11	3	318/799 and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.))	USPAT	2003/05/08 12:54
12	1	(318/560 318/615 318/561) and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.)) and numerical	USPAT	2003/05/08 12:56
13	1	(318/$) and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.)) and numerical	USPAT	2003/05/08 13:01
14	0	(318/689 318/431 318/432) and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.)) and numerical	USPAT	2003/05/08 13:02

15	6	(318/689 318/431 318/432) and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.))	USPAT	2003/05/08 13:06
16	5	(318/806 318/807) and (((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) ((electric same motor same control$5 same simulat$3).bsum. or (electric same motor same control$5 same simulat$3).ab.))	USPAT	2003/05/08 13:06
-	112	700/170	USPAT; US-PGPUB	2003/05/06 16:37
-	7	700/170 and simulat$4 and numerical	USPAT; US-PGPUB	2003/05/06 16:57
-	1	700/170 and (simulat$4 same numerical)	USPAT; US-PGPUB	2003/05/06 17:00
-	5	(simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and PI and PID	USPAT; US-PGPUB	2003/05/06 17:53
-	0	((simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and PI and PID) and transmission	USPAT; US-PGPUB	2003/05/06 17:40
-	1	6,011,373.pn.	USPAT; US-PGPUB	2003/05/06 17:40
-	27	(simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and (PI or PID)	USPAT; US-PGPUB	2003/05/06 17:54
-	22	((simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and (PI or PID)) not ((simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and PI and PID)	USPAT; US-PGPUB	2003/05/06 18:44
-	10	((simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and (PI or PID)) not ((simulat$4 same numerical) and motor and torque and (speed rate velocity) and position and PI and PID) and (motor.bsum. or motor.ab.)	USPAT; US-PGPUB	2003/05/06 18:45
-	69396	electric same motor same control$5).(ti. ab.	USPAT; US-PGPUB	2003/05/07 12:50
-	8143	(electric same motor same control$5).ti. or (electric same motor same control$5).ab.	USPAT; US-PGPUB	2003/05/07 12:53
-	63	(electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.	USPAT; US-PGPUB	2003/05/07 16:21
-	0	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque and PI and PID	USPAT; US-PGPUB	2003/05/07 13:07
-	28	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque	USPAT; US-PGPUB	2003/05/07 13:18
-	0	(((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and (speed velocity rate) and podition	USPAT; US-PGPUB	2003/05/07 13:12

-	21	(((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and (speed velocity rate) and position	USPAT; US-PGPUB	2003/05/08 12:21
-	11	((((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and (speed velocity rate) and position) and compensat$3	USPAT; US-PGPUB	2003/05/07 13:17
-	0	(((((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and (speed velocity rate) and position) and compensat$3) and numerical	USPAT; US-PGPUB	2003/05/07 13:17
-	1	(((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and numerical	USPAT; US-PGPUB	2003/05/07 13:18
-	1	((((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and electric and motor and control$5 and torque) and (speed velocity rate) and position) and (simulat$3 same numerical)	USPAT; US-PGPUB	2003/05/07 14:18
-	63	(electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.	USPAT; US-PGPUB	2003/05/08 12:20
-	0	((electric same motor same control$5 same simulat$3).ti. or (electric same motor same control$5 same simulat$3).ab.) and (PI and PID) and numerical	USPAT; US-PGPUB	2003/05/07 16:28
-	0	(electric same motor same control$5 same simulat$3) and (PI and PID) and numerical	USPAT; US-PGPUB	2003/05/07 16:35
-	0	((electric same motor same control$5) and (PI and PID) and numerical and simulat$3) and (simulat$3 near numerical)	USPAT; US-PGPUB	2003/05/07 16:36
-	0	((electric same motor same control$5) and (PI and PID) and numerical and simulat$3) and (simulat$3 same numerical)	USPAT; US-PGPUB	2003/05/07 16:36
-	7	(electric same motor same control$5) and (PI and PID) and numerical and simulat$3	USPAT; US-PGPUB	2003/05/07 16:37
-	115	(electric same motor same control$5) and (PI same PID)	USPAT; US-PGPUB	2003/05/07 16:41
-	8	((electric same motor same control$5) and (PI same PID)) and numerical	USPAT; US-PGPUB	2003/05/07 17:34
-	7	(((electric same motor same control$5) and (PI same PID)) and numerical) and compensat$3	USPAT; US-PGPUB	2003/05/07 17:35
-	4	(((electric same motor same control$5) and (PI same PID)) and numerical) and compensat$3 and compensator	USPAT; US-PGPUB	2003/05/07 17:35
-	8	(US-6356799-$ or US-6191513-$ or US-5726879-$ or US-4488242-$ or US-6505085-$ or US-5428285-$ or US-5206575-$ or US-6198246-$).did.	USPAT	2003/05/07 18:25
-	4	((US-6356799-$ or US-6191513-$ or US-5726879-$ or US-4488242-$ or US-6505085-$ or US-5428285-$ or US-5206575-$ or US-6198246-$).did.) and (parameter same simulat$3)	USPAT; US-PGPUB	2003/05/07 18:26
-	8	(US-6198246-$ or US-5206575-$ or US-6505085-$ or US-6356799-$ or US-6191513-$ or US-5726879-$ or US-5428285-$ or US-4488242-$).did.	USPAT	2003/05/08 10:28

-	2	((US-6198246-$ or US-5206575-$ or US-6505085-$ or US-6356799-$ or US-6191513-$ or US-5726879-$ or US-5428285-$ or US-4488242-$).did.) and simulat$3.bsum.	USPAT; US-PGPUB	2003/05/08 10:29